



# ***Electromagnetic Formation Flight (EMFF) and Applications to TPF***

**TPF Expo**

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David W. Miller

Associate Professor

Director, Space Systems Laboratory

Department of Aeronautics and Astronautics

Massachusetts Institute of Technology

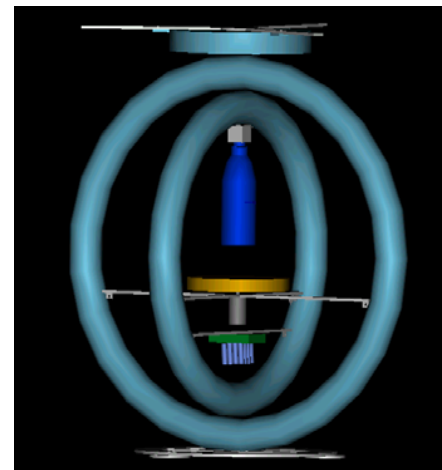
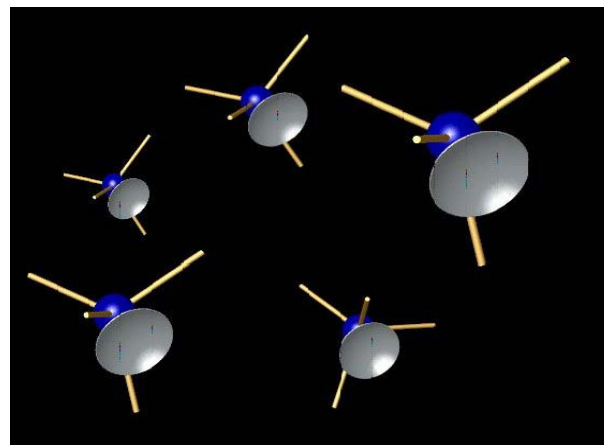
[millerd@mit.edu](mailto:millerd@mit.edu)

<http://ssl.mit.edu>

<http://cdio-prime.mit.edu>

Presented by: Laila M. Elias

Graduate Research Assistant





# Outline



- **Motivation**
- **Fundamental Principles**
- **Mission Applicability**
- **MIT EMFFORCE Testbed**
- **Conclusions**

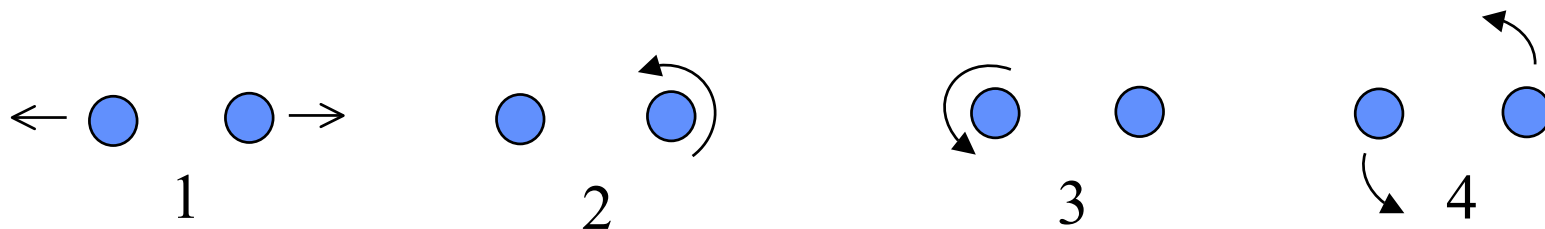


# Motivation for EMFF



- **Traditional propulsion uses propellant as a reaction mass**
- **Advantages**
  - Ability to move center of mass of spacecraft  
(Momentum conserved when propellant is included)
  - Independent (and complete) control of each spacecraft
- **Disadvantages**
  - Propellant is a limited resource
  - Momentum conservation requires that the necessary propellant mass increase exponentially with the velocity increment ( $\Delta V$ )
  - Propellant can be a contaminant to precision optics
- **Is there a technique that does not consume propellant?**
  - **Electromagnetic Formation Flight (EMFF)**

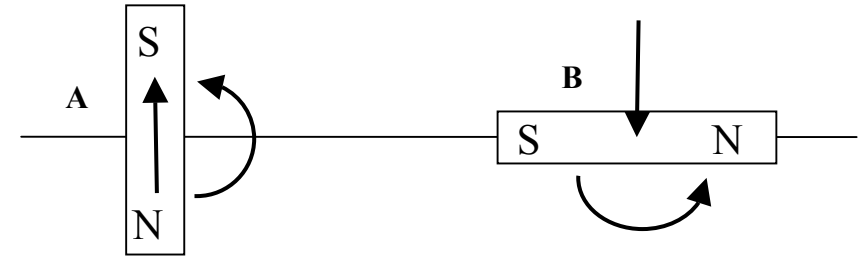
- Yes, **inter-spacecraft** forces can be used!
  - ... provided it is not necessary to alter the center of mass of the system.
- What forces must be transmitted between satellites to allow for all **relative** degrees of freedom to be controlled?
  - In 2-D,  $N$  spacecraft have  $3N$  DOF, but we are only interested in controlling (and able to control)  $3N-2$  (no translation of the center of mass)
  - For 2 spacecraft, that's 4 DOF:



- (1)-(3) can be controlled using **inter-spacecraft axial forces**
- (2)-(3) can be controlled using **reaction wheel torques**
- (4) requires **inter-spacecraft transverse forces**, which can be created using **electromagnetic dipoles**

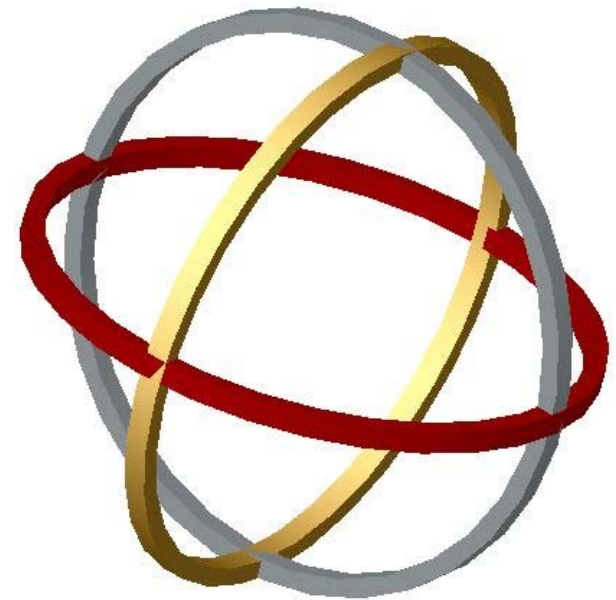


Axial forces maintain steady array rotation



Transverse forces initiate array spin-up

- Each vehicle has 3 orthogonal electromagnetic coils.
- In the far field, dipoles add as vectors.
  - 3 vector “components” on each vehicle form one “steerable” magnetic dipole
  - Electronic steering decouples the coils from the spacecraft rotational dynamics
- A reaction wheel assembly with 3 orthogonal wheels provides counter torques to maintain attitude



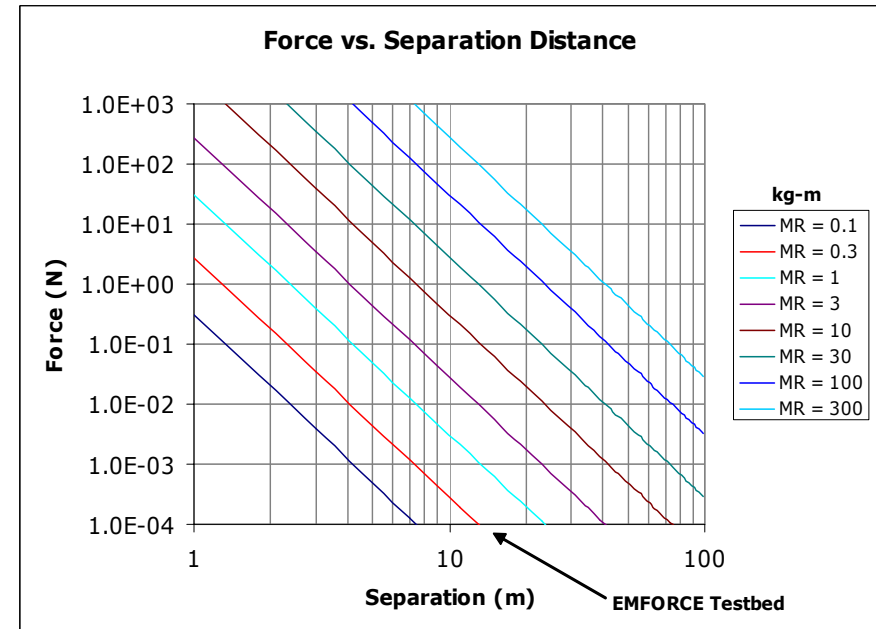
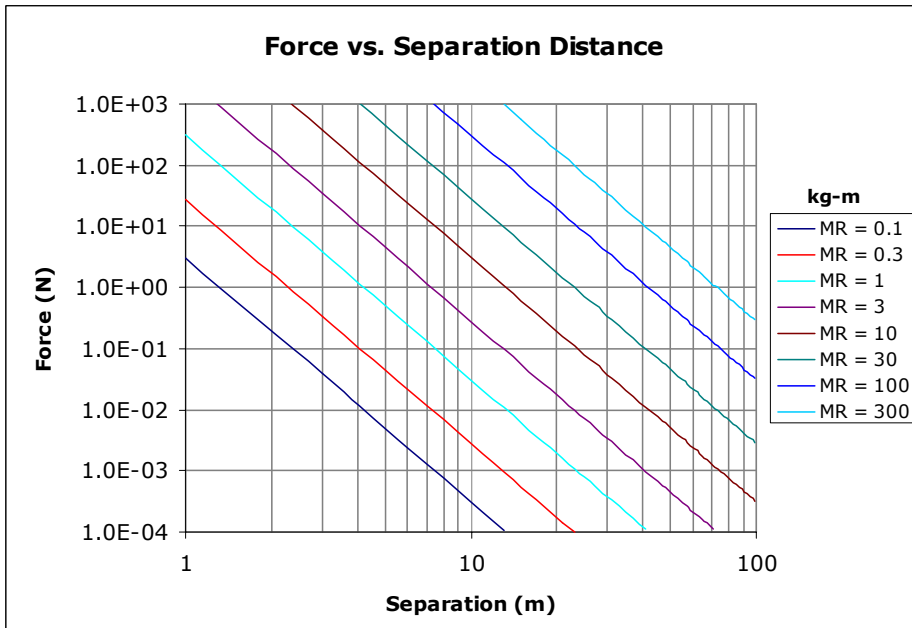
# How Far Apart Will They Work?

Axial force generated by a set of coils:

$$F \sim 31.2 (M_C R_C)^2 \frac{1}{s^4}$$

The graph to the right shows a family of curves for various products of  $M_C$  and  $R_C$

$$\frac{3}{2}(10^{-7})\left(\frac{I_C}{\rho}\right)^2 = 312 \frac{\text{m}^3}{\text{kg}\cdot\text{s}^2}$$

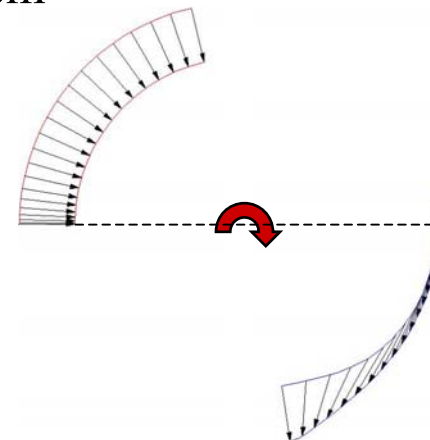
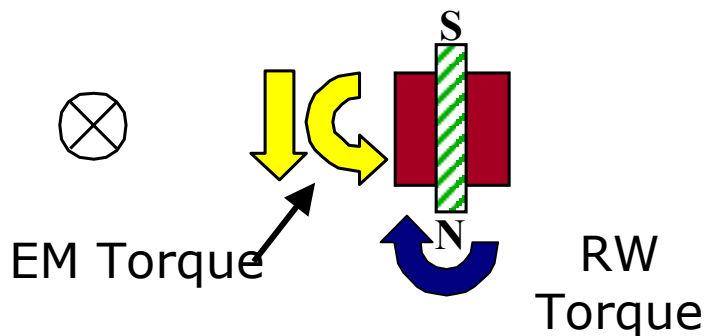
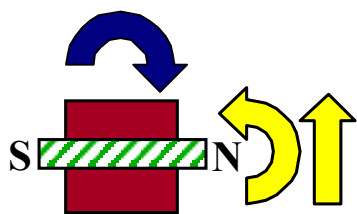


$$\frac{3}{2}(10^{-7})\left(\frac{I_C}{\rho}\right)^2 = 31.2 \frac{\text{m}^3}{\text{kg}\cdot\text{s}^2}$$

Example:

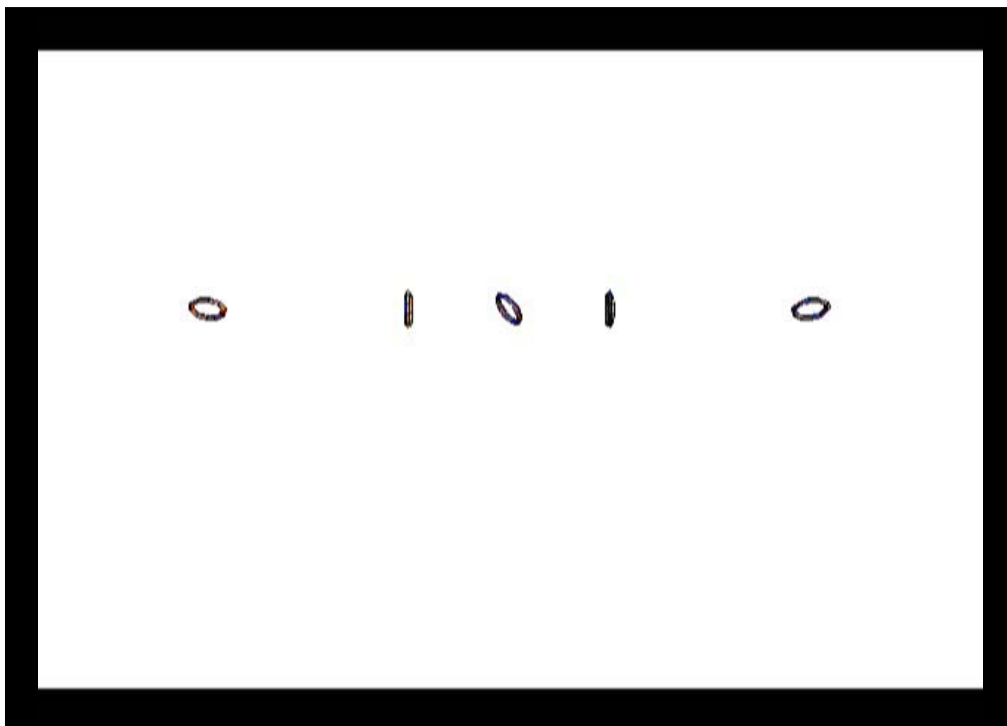
- 300 kg satellite, 2 m across, needs 10 mN of thrust, want  $M_C < 30$  kg
- EMFF effective up to 40 meters
- 6MA/cm<sup>2</sup> extends to 560 meters

- Spin-up/spin-down
  - Spin-up to rotating array
  - Spin-down to reoriented baseline
- Electromagnets (EMs) exert forces/torques on each other
  - Equal and opposite “shearing” forces
  - Torques in the same direction
- Reaction wheels (RWs) are used to counteract EM torques
  - Initial torque caused by perpendicular-dipole orientation
  - RWs counter-torque to command EM orientation
  - Angular momentum conserved by shearing of the system

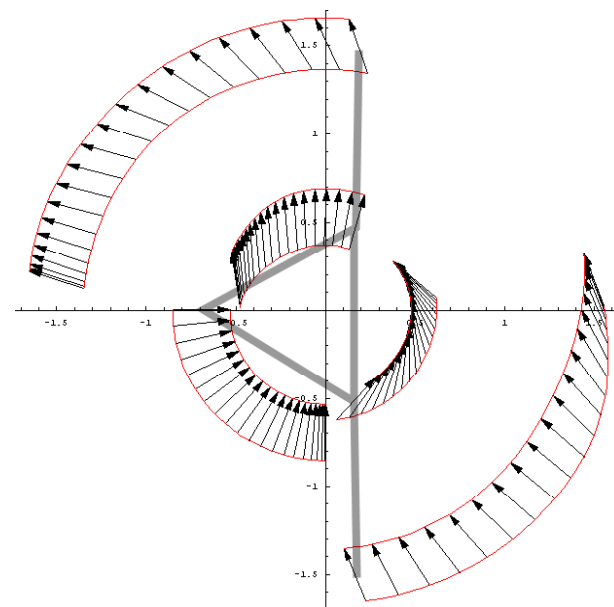


# Satellite Formation Spin-Up

- Spin-up of **complex formations** can also be achieved using magnetic dipoles.
- Formations are not restricted to linear arrays!



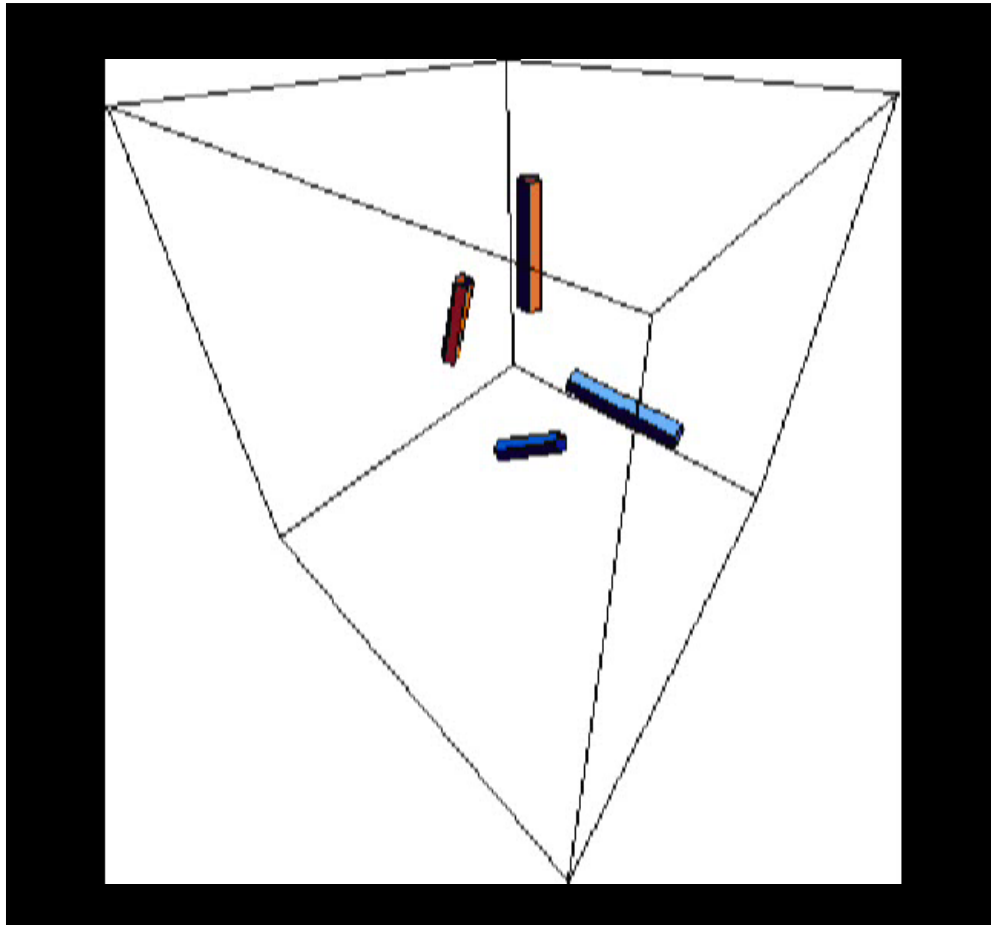
Video: 600 kg s/c, 75m diameter formation, 0.5 rev/hr



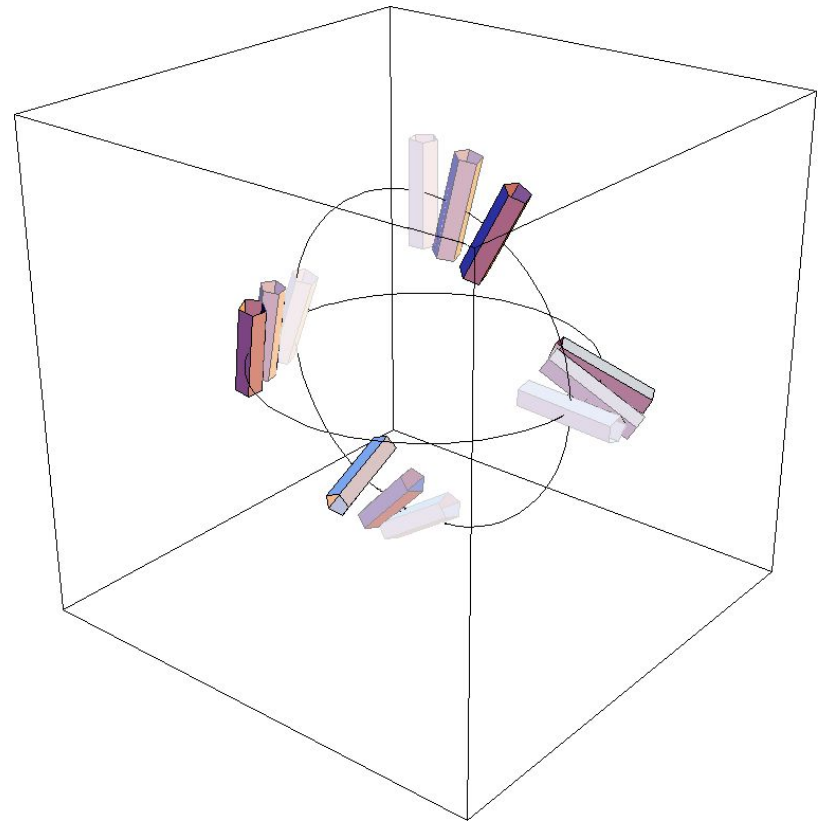


# 3-D Formations

- We also have the ability to solve for complex 3D motion of satellites.



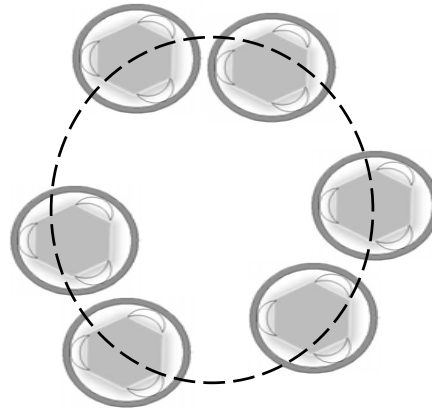
Video: Complex 3-D Motion



## Sparse Apertures



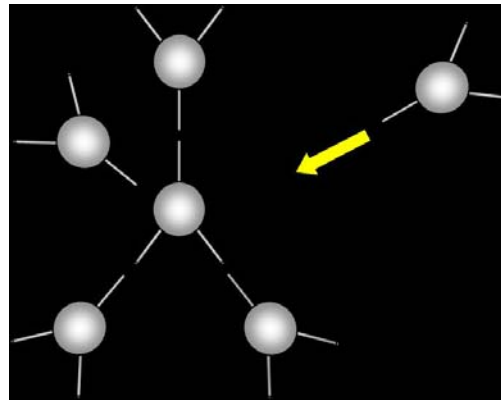
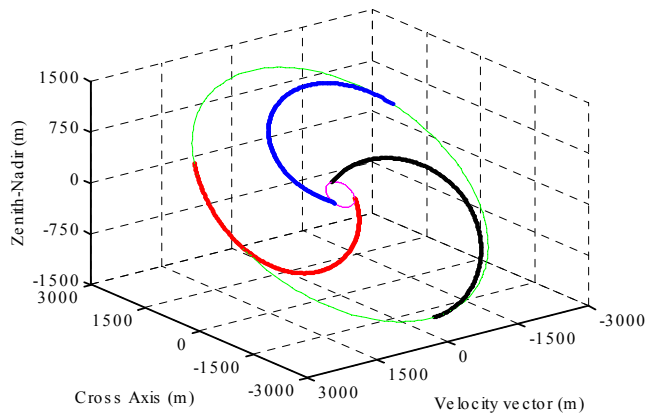
## Distributed Optics



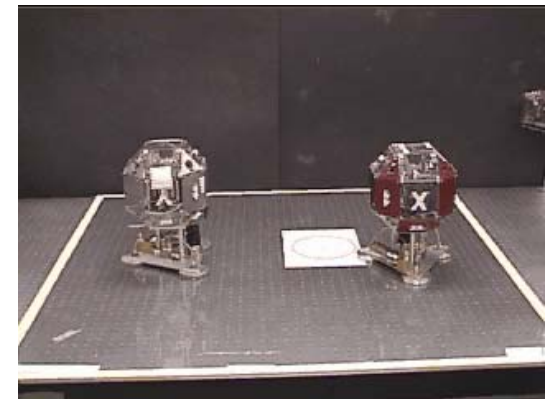
## EMFF Secondary Mirrors



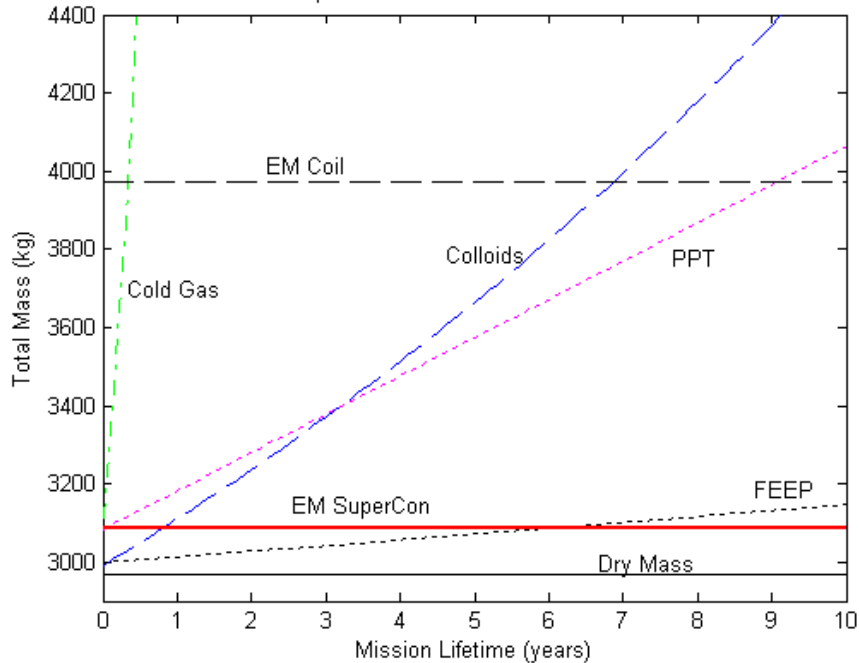
## Cluster Reconfiguration



## Docking

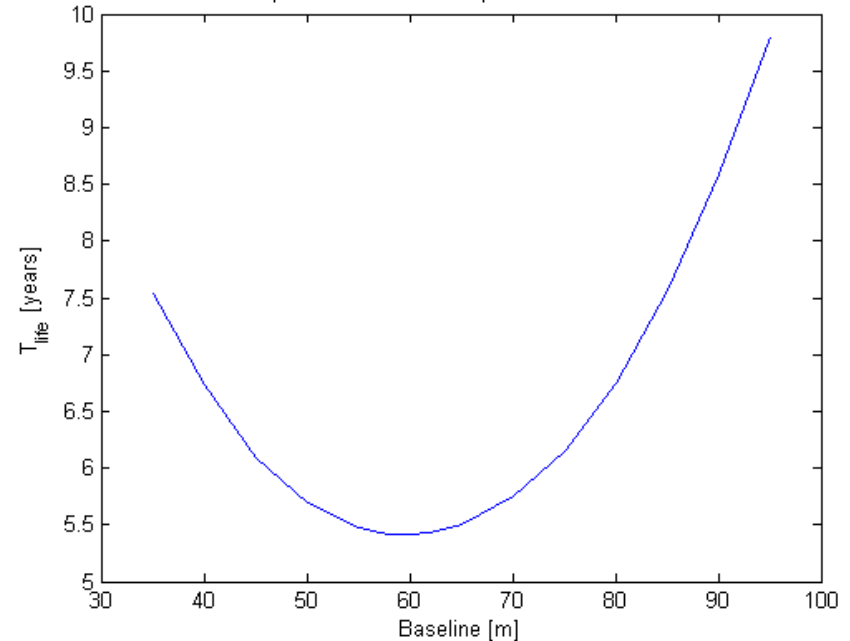


Mass comparison for 40 m baseline - 2 Hrs Rotation



- **Cold Gas** - Low  $I_{sp}$ , high propellant requirements
  - Not viable option
- **PPTs and Colloids** - Higher  $I_{sp}$ 
  - still significant propellant over mission lifetime
- **FEEPs** – Best for 5 yr mission lifetime
  - Must consider contamination issue
  - Only 15 kg mass savings over EMFF @ 5 yr mark

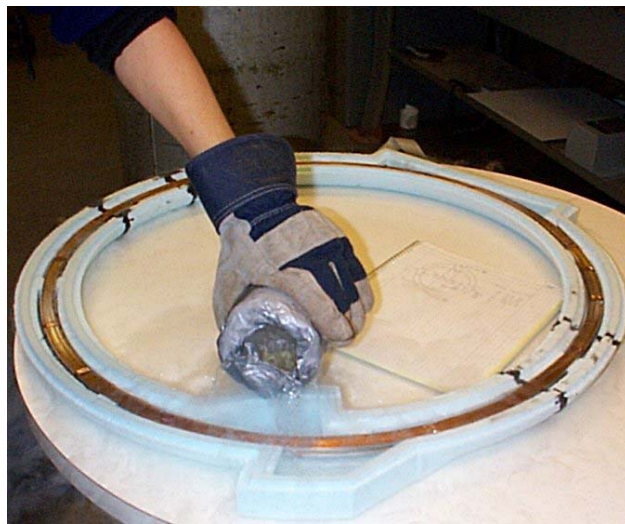
Mission life break point where EMFF Superconductor Mass < FEEP's Mass

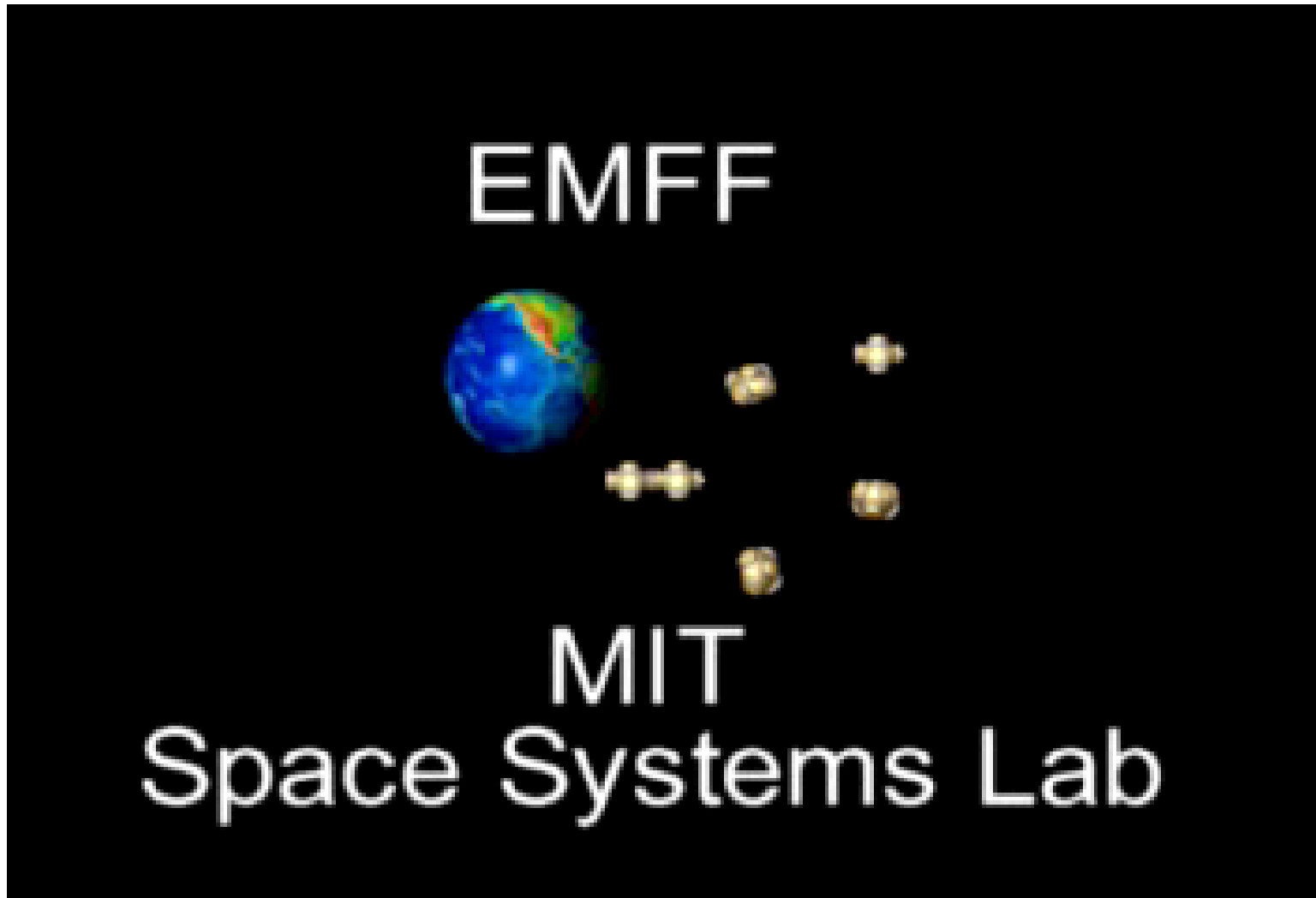


- **EM coil** ( $R = 4$  m) ( $M_{tot} = 3971$  kg)
  - Less ideal option when compared to FEEPs even for long mission lifetime
- **EM Super Conducting Coil** ( $R = 2$  m) ( $M_{tot} = 3050$  kg)
  - Best mass option for missions > 6.8 years
  - No additional mass to increase mission lifetime
  - Additional mass may be necessary for CG offset
    - Estimated as ~80 kg

# EMFForce Testbed Overview

- 2-D testbed traceable to 3-D
- Exercise all controllable degrees of freedom
- High temperature superconducting wire (HTS)
  - Operates at  $9\text{kAmps/cm}^2$  (Capable of  $13\text{kAmps/cm}^2$ )
  - HTS demonstrations at  $6\text{MAmps/cm}^2$
  - 100 wraps, Outer diameter  $\sim 0.8\text{ m}$ , Operates at  $77\text{K}$
- Four D-cells drive 70 Amps for 40 minutes





Note: to hear audio narration, turn on your computer's sound.



# Conclusions



- Many types of missions can benefit from propellantless relative control between satellites
  - Provides longer lifetime (even for aggressive maneuvers)
  - Reduces contamination and degradation
- Optimal system sizing has been determined for relatively small satellite arrays. Currently larger formations are being investigated
- Preliminary validation with the MIT Testbed has been achieved, and more complex maneuver profiles will be accomplished with future upgrades